

SilverSurfer polling mode driver

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;-----
; SilverSurfer polling mode driver (w)
2001 Groepaz/Hitmen
; - this one is optimized for size and reliability (rather than maximum
speed or efficiency)
;-----
;-----
; ss_detect          detect silversurfer, returns CARRY=1 on error
; ss_init            init uart, call with baudrate divisor lowbyte in A
; ss_getchr          get byte (blocking) - returns next byte in A
; ss_getchr2         get byte (non blocking, returns byte in A or CARRY=1
- error)
; ss_putchr          sends byte in A
;-----
;-----
; all functions except ss_detect and ss_init use/modify AKKU only.
;-----
;-----

.include "silversurfer.inc" ; fifo defines

                .export ss_detect,ss_init
                .export ss_getchr,ss_getchr2,ss_putchr

                .export ss_stat_reciever_ready
                .export ss_stat_data_available
                .export ss_stat_transmit_ready
                .export ss_pause,ss_unpause

;-----
;-----
; detect silversurfer, returns CARRY=1 on error
;-----
;-----

ss_detect:

    ;
    ; enable ssurfer-port
    ;

    lda $de01
    ora #$01
    sta $de01

    ;

```

```
        ; check if scratch-register available
        ;

        ldx #$00
@l1:    stx fifo_scratch
        cpx fifo_scratch
        bne @sk1

        inx
        bne @l1

        ; ok
        clc
        rts

@sk1:   ; error
        sec
        rts

;-----
;-----
; init uart, call with baudrate divisor lowbyte in A
;-----
;-----
;
;   9600      $30
;  19200     $18
;  38400     $0c
;  57600     $08
; 115000     $04
;
;-----
;-----

ss_init:
        tax

        ;
        ; enable ssurfer-port
        ;

        lda $de01
        ora #$01
        sta $de01

        ;
        ; init and set baudrate
        ;
```

```
        lda #%10000111
        sta fifo_fcr

; that delay thing really needed ?!
; (original datasheet mentions a delay here)
;     ldy #$00
;     dey
;     bny *-1

; set dlab
lda #%10000011
sta fifo_lcr

; set baudrate

stx fifo_dll
lda #$00
sta fifo_dlm

; reset dlab
lda #%00000011
sta fifo_lcr

; disable nmi's from ssurfer
lda #%00000000
sta fifo_ier

; activate dtr
jmp ss_pause

;-----
-----
; check if data available
; no data:   AKKU=0
; data:     AKKU!=0
;-----
-----
ss_stat_data_available:
        lda fifo_lsr
        and #%00000001
        rts

;-----
-----
; check if transmit register empty
; busy:     AKKU=0
; empty:    AKKU!=0
;-----
-----
ss_stat_transmit_ready:
        lda fifo_lsr
        and #%00100000
```

```

        rts
;-----
;-----
; check if reciever ready
; busy:   AKKU=0
; ready:  AKKU!=0
;-----
;-----
ss_stat_reciever_ready:
    ; check cts
    lda fifo_msr
    and #%00010000
    rts
;-----
;-----
; Flow-Control
;-----
;-----
ss_unpause:
    ; activate rts
    lda #%00000011
    sta fifo_mcr
    rts
ss_pause:
    ; deactivate rts
    lda #%00000001
    sta fifo_mcr
    rts
;-----
;-----
; get byte (non blocking, returns byte in A or CARRY=1 - error)
;-----
;-----
ss_getchr2:
    ; check if byte available
    jsr ss_stat_data_available
    bne sk32 ; yes

    ; release flow-control
    jsr ss_unpause
sk32:
    ; set flow-control
    jsr ss_pause

    ; check if byte available
    jsr ss_stat_data_available
    bne sk33 ; yes
    sec
    rts
sk33:
    ; get byte

```

```
        lda fifo_rxd
        clc
        rts

;-----
; get byte (blocking) - returns next byte in A
;-----

ss_getchr:

@lp1:
        jsr ss_getchr2
        bcs @lp1 ; no byte read
        rts

;-----
; send byte in A (blocking) - waits until byte can be send
;-----

ss_putchr:
        pha

        ; wait until reciever is ready to recieve
l2:
        jsr ss_stat_reciever_ready
        beq l2

        ; wait until send buffer is empty
l1:
        jsr ss_stat_transmit_ready
        beq l1

        ; send byte
        pla
        sta fifo_txd
        rts

;-----
```

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<https://codebase64.org/> - **Codebase 64 wiki**

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